

# « Automatic program verification by Lagrangian relaxation and semidefinite programming »

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# Aperitif: Relational semantics of loops



# Relational semantics of loops

while B do C od

- $x \in \mathbb{R}/\mathbb{Q}/\mathbb{Z}$ : values of the loop variables *before* a loop iteration
- $x' \in \mathbb{R}/\mathbb{Q}/\mathbb{Z}$ : values of the loop variables *after* a loop iteration
- $\llbracket B; C \rrbracket(x, x')$ : relational semantics of *one loop iteration*
- $\llbracket B; C \rrbracket(x, x') = \bigwedge_{i=1}^N \sigma_i(x, x') \geq 0$  (where  $\geq$  is  $>$ ,  $\geq$  or  $=$ )
- not a restriction for numerical programs



# Example of quadratic form program (factorial)

$$[x \ x'] A [x \ x']^\top + 2[x \ x'] q + r \geq 0$$

```

n := 0;
f := 1;
while (f <= N) do
    n := n + 1;
    f := n * f
od
    
```

```

-1.f +1.N >= 0
+1.n >= 0
+1.f -1 >= 0
-1.n +1.n' -1 = 0
+1.N -1.N' = 0
-1.f.n' +1.f' = 0
    
```

$$[nfNn'f'N'] \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} n \\ f \\ N \\ n' \\ f' \\ N' \end{bmatrix} + 2[nfNn'f'N'] \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \frac{1}{2} \\ 0 \end{bmatrix} + 0 = 0$$



# Appetiser: Floyd/Hoare/Naur correctness proof method



# Invariance proof

Given a loop precondition  $P$ , find an unknown loop **invariant**  $I$  such that:

- The invariant is **initial**:

$$\forall x : P(x) \Rightarrow I(x)$$

- The invariant is **inductive**:

$$\forall x, x' : I(x) \wedge \llbracket B; C \rrbracket(x, x') \Rightarrow I(x')$$



# Invariance proof for numerical programs

Given a loop precondition  $P(x) \geq 0$ , find an unknown loop invariant  $I(x) \geq 0$  such that:

- The invariant is *initial*:

$$\forall x : P(x) \geq 0 \Rightarrow I(x) \geq 0$$

- The invariant is *inductive*:

$$\forall x, x' : \left( I(x) \geq 0 \wedge \bigwedge_{i=1}^N \sigma_i(x, x') \geq 0 \right) \Rightarrow I(x') \geq 0$$



# Termination proof

Given a loop invariant  $I$ , find an  $\mathbb{R}/\mathbb{Q}/\mathbb{Z}$ -valued unknown rank function  $r$  such that:

- The rank is *nonnegative*:

$$\forall x : I(x) \Rightarrow r(x) \geq 0$$

- The rank is *strictly decreasing*:

$$\forall x, x' : I(x) \wedge \llbracket B; C \rrbracket(x, x') \Rightarrow r(x') \leq r(x) - \eta$$

$\eta = 1$  for  $\mathbb{Z}$ ,  $\eta > 0$  for  $\mathbb{R}/\mathbb{Q}$  to avoid Zeno  $\frac{1}{2}, \frac{1}{4}, \frac{1}{8} \dots$





Wine service:  
Iterated forward/backward  
static analysis for  
conditional termination



# Conditional termination

- In general a loop **does not terminate** for all initial **values** of the variables
- In that case we can find **no rank function**!
- We must automatically determine a necessary **loop precondition**
- We use a **iterated forward/backward static analysis** ... with an **auxiliary counter** counting the number of remaining iterations down to zero



# Arithmetic mean example, polyhedral abstraction without auxiliary counter)

```
{x>=y}  
  while (x <> y) do  
    {x>=y+2}  
    x := x - 1;  
    {x>=y+1}  
    y := y + 1  
    {x>=y}  
  od  
{x=y}
```



# Arithmetic mean example, polyhedral abstraction with auxiliary counter

```
{x=y+2k, x ≥ y}  
while (x <> y) do  
  {x=y+2k, x ≥ y+2}  
  k := k - 1;  
  {x=y+2k+2, x ≥ y+2}  
  x := x - 1;  
  {x=y+2k+1, x ≥ y+1}  
  y := y + 1  
  {x=y+2k, x ≥ y}  
od  
{x=y, k=0}  
assume (k = 0)  
{x=y, k=0}
```



# Entrée: Abstraction to parametric constraints



# Parametric constraints

- Fix the form of the unknown ( $I(x) \geq 0 / r(x) \geq 0$ ) using parameters  $a$  in the form  $Q(a, x) \geq 0$
- This is an abstraction
- Examples:
  - $r(x, y) = a.x + b.y + c$
  - $I(x, x') = a.x^2 + b.x.x' + c.x'^2 + d.x + e.x' + f$



## Solving the constraints

- The invariance [termination] problems have the form:

$$\begin{aligned} & \exists a : \forall x, x' : \\ & \left( [Q(a, x) \geq 0 \wedge] \bigwedge_{k=1}^n C_k(x, x') \geq 0 \right) \\ & \Rightarrow \\ & Q'(a, x, x') \geq 0 \end{aligned}$$

- Find an algorithm to effectively compute  $a$ !



# Problems

In order to compute  $a$ :

- How to handle  $\wedge$  ?
- How to get rid of the implication  $\Rightarrow$  ?
  - Lagrangian relaxation
- How to get rid of the universal quantification  $\forall$  ?
- How to handle  $\vee$  ?
  - quantifier elimination (does not scale up)
  - mathematical programming





# Algorithmically interesting cases

- linear inequalities
  - linear programming<sup>1</sup>
- linear matrix inequalities (LMI)/quadratic forms
- bilinear matrix inequalities (BMI)
  - semidefinite programming
- semialgebraic sets
  - polynomial quantifier elimination, or
  - relaxation with semidefinite programming

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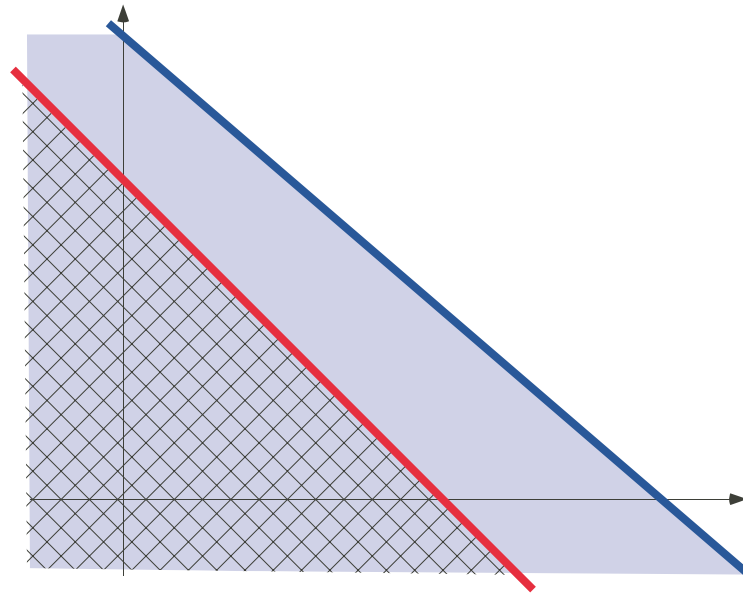
<sup>1</sup> Already explored for invariants by Sankaranarayanan, Spima, Manna (CAV'03, SAS'04, heuristic solver) and for termination by Podelski & Rybalchenko (VMCAI'03, Lagrange coefficients eliminated by hand to reduce to linear programming so no disjunctions, no tests, etc).



First main course:  
Lagrangian relaxation  
for implication elimination



# Example of linear Lagrangian relaxation



$A \Rightarrow B$  (assuming  $A \neq \emptyset$ )

$\Leftarrow$  (soundness)

$\Rightarrow$  (completeness)

border of  $A$  parallel to border of  $B$



# Lagrangian relaxation, formally

Let  $\mathbb{V}$  be a finite dimensional linear vector space,  $N > 0$   
and  $\forall k \in [1, N] : \sigma_k \in \mathbb{V} \mapsto \mathbb{R}$ .

$$\forall x \in \mathbb{V} : \left( \bigwedge_{k=1}^N \sigma_k(x) \geq 0 \right) \Rightarrow (\sigma_0(x) \geq 0)$$

$\Leftarrow$  soundness (Lagrange)  
 $\Rightarrow$  completeness (*lossless*)  
 $\nRightarrow$  ncompleteness (*lossy*)

$$\exists \lambda \in [1, N] \mapsto \mathbb{R}_* : \forall x \in \mathbb{V} : \sigma_0(x) - \sum_{k=1}^N \lambda_k \sigma_k(x) \geq 0$$

relaxation = approximation,  $\lambda_i$  = Lagrange coefficients



# Lagrangian relaxation, completeness cases

- Linear case  
(affine Farkas' lemma)
- Linear case with at most 2 quadratic constraints  
(Yakubovich's S-procedure)



# Lagrangian relaxation of the constraints

$$\exists a : \forall x, x' : [Q(a, x) \geq 0 \wedge] \bigwedge_{k=1}^n C_k(x, x') \geq 0$$

$$\Rightarrow Q'(a, x, x') \geq 0$$

$\Leftarrow$  (is relaxed into)

$$\exists a : [\exists \lambda \geq 0] : \exists \lambda_k \geq 0 : \forall x, x' :$$

$$Q'(a, x, x')[-\lambda.Q(a, x)] - \sum_{k=1}^n \lambda_k.C_k(x, x') \geq 0$$

$\uparrow$  linear in  $a$

$\uparrow$  linear in the  $\lambda_k$

$\uparrow$  bilinear in  $a$  &  $\lambda$



Second main course:  
Mathematical programming  
for quantifier elimination



# Mathematical programming

$$\exists x \in \mathbb{R}^n: \bigwedge_{i=1}^N g_i(x) \geq 0$$

[Minimizing  $f(x)$ ]

**feasibility problem** : find a solution to the constraints

**optimization problem** : find a solution, minimizing  $f(x)$





# Semidefinite programming

$$\exists x \in \mathbb{R}^n: \quad M(x) \succcurlyeq 0$$

[Minimizing  $cx$ ]

Where the linear matrix inequality is

$$M(x) = M_0 + \sum_{k=1}^n x_k M_k$$

with symmetric matrices ( $M_k = M_k^\top$ ) and the positive semidefiniteness is

$$M(x) \succcurlyeq 0 = \forall X \in \mathbb{R}^N : X^\top M(x) X \geq 0$$



# Semidefinite programming, once again

Feasibility is:

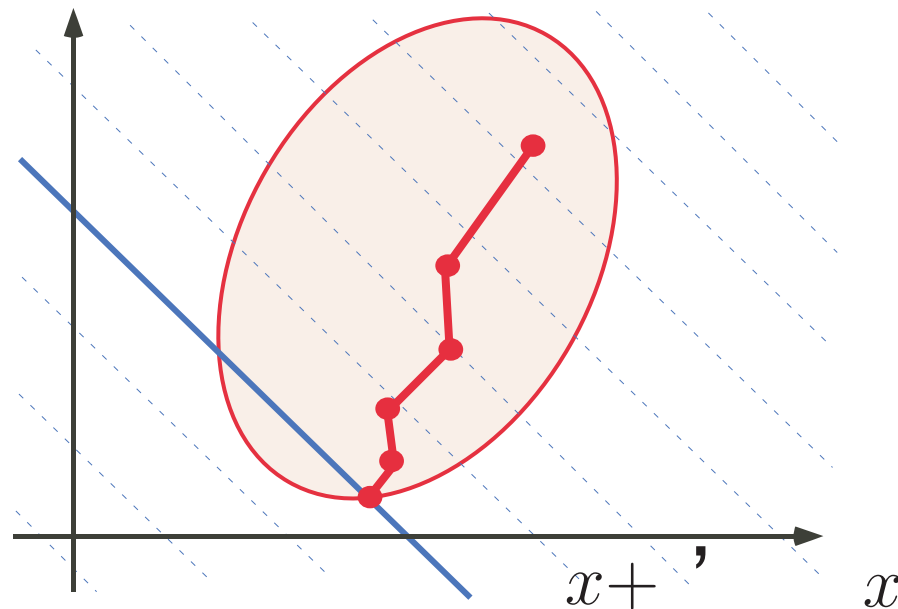
$$\exists x \in \mathbb{R}^n : \forall X \in \mathbb{R}^N : X^\top \left( M_0 + \sum_{k=1}^n x_k M_k \right) X \geq 0$$

of the form of the (linear) formulæ we are interested in for programs with linear matricial semantics.



# Interior point method for semidefinite programming

- Nesterov & Nemirovskii 1988, polynomial in worst case and good in practice (thousands of variables)



- Various path strategies e.g. “stay in the middle”



# Semidefinite programming solvers

Numerous solvers available under MATLAB<sup>®</sup>, a.o.:

- `lmilab`: P. Gahinet, A. Nemirovskii, A.J. Laub, M. Chilali
- `Sdplr`: S. Burer, R. Monteiro, C. Choi
- `Sdpt3`: R. Tütüncü, K. Toh, M. Todd
- `SeDuMi`: J. Sturm
- `bnb`: J. Löfberg (integer semidefinite programming)

Common interfaces to these solvers, a.o.:

- `Yalmip`: J. Löfberg

Sometime need some help (feasibility radius, shift,...)



# Recent generalization to bilinear matrix inequalities

– penbmi: M. Kočvara, M. Stingl

Feasibility is:

$\exists x \in \mathbb{R}^n : \forall X \in \mathbb{R}^N :$

$$X^\top \left( M_0 + \sum_{j=1}^n x_j M_j + \sum_{k=1}^n \sum_{\ell=1}^n x_k x_\ell M'_{k\ell} \right) X \geq 0$$

of the form of the (bilinear) formulæ we are interested in!



# Skipping the cheese ...



## Not enough time for ...

- Disjunctions in the loop test?
- Conditionals in the loop body?
- Nested loops?
- Concurrency?
- Fair parallelism?
- Semi-algebraic/polynomial programs?
- Data structures?



# Desert Invariance and Termination Examples





# Termination of a linear program

<code>{y &gt;= 1}</code>	←	termination precondition de-
<code>while (x &gt;= 1) do</code>		termined by iterated for-
<code>x := x - y</code>		ward/backward polyhedral
<code>od</code>		analysis

lmilab:

$r(x,y) = +2.178955e+12.x + 1.453116e+12.y - 1.451513e+12$

lmilab (with feasibility radius of  $1.0e4$ ):

$r(x,y) = +4.074723e+03.x + 2.786715e+03.y + 1.549410e+03$

sedumi:

$r(x,y) = +2.271450e+03.x + 1.810903e+03.y - 3.623997e+03$

bnb (integer semidefinite programming)<sup>2</sup>:  $r(x,y) = +2.x + 2.y - 3$

---

<sup>2</sup> still in infancy!



# Termination of the arithmetic mean

```
{x=y+2k, x>=y}  
while (x <> y) do  
    k := k - 1;  
    x := x - 1;  
    y := y + 1  
od  
{assert (k = 0)}
```

← termination precondition  
determined by iterated  
forward/backward poly-  
hedral analysis

lmilab:

```
r(x,y,k) = +1.382113e+03.x -1.382113e+03.y +4.978695e+03.k  
+2.711732e+03
```



# Termination of the Euclidean division

```
1:  {y>=1}          ← termination precondition determined
   q := 0;          by iterated forward/backward polyhe-
2:  {q=0,y>=1}      dral analysis
   r := x;
3:  {x=r,q=0,y>=1}
   while (y <= r) do
     4:  {y<=r,q>=0}
         r := - y + r;
     5:  {r>=0,q>=0}
         q := q + 1
     6:  {r>=0,q>=1}
   od
7:  {q>=0,y>=r+1}
```

bnb:

$$r(y,q,r) = -2.y + 2.q + 4.r$$

Floyd's proposal  $r(x,y,q,r) = x - q$  is more intuitive but requires to discover the nonlinear loop invariant  $x = r + qy$ .



# Termination of a quadratic program: factorial

<code>{true}</code>	← termination precondition
<code>n := 0;</code>	determined by iterated forward/backward polyhedral analysis
<code>f := 1;</code>	
<code>while (f &lt;= N) do</code>	
<code>n := n + 1;</code>	
<code>f := n * f</code>	
<code>od</code>	

sedumi (with feasibility radius of  $1.0e+3$ ):

$$r(n, f, N) = -9.993462e-01.n + 1.617225e-04.f + 2.688476e+02.N + 8.745232e+02$$


# Loop body with tests

```
while (x < y) do
  if (i >= 0) then
    x := x+i+1
  else
    y := y+i
  fi
od
```

lmilab:

$r(i,x,y) = -2.252791e-09.i - 4.355697e+07.x + 4.355697e+07.y + 5.502903e+08$



# Quadratic termination of linear loop

$\{n \geq 0\}$

$i := n; j := n;$

while ( $i \neq 0$ ) do

  if ( $j > 0$ ) then

$j := j - 1$

  else

$j := n; i := i - 1$

  fi

od

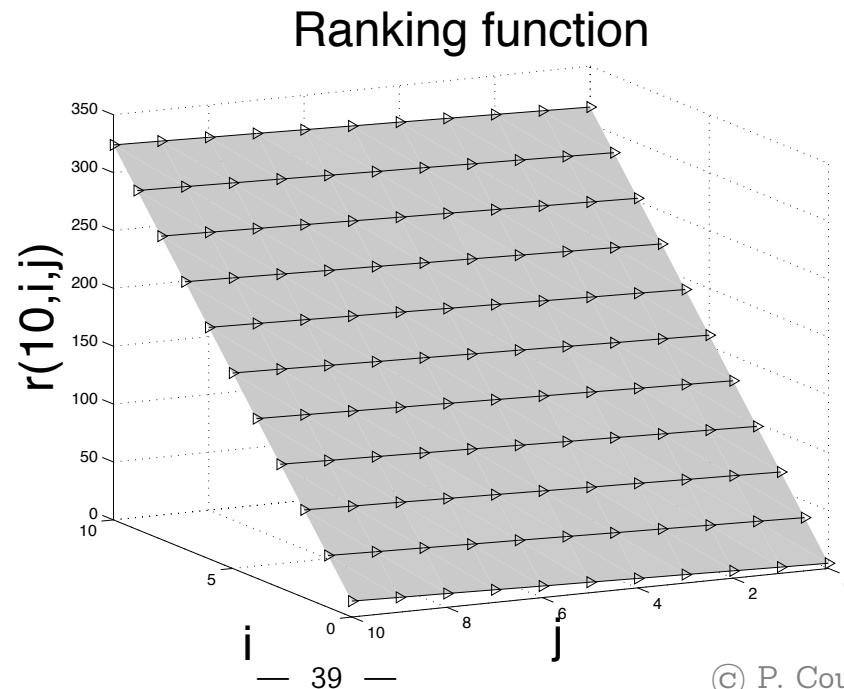
← termination precondition  
determined by iterated forward/backward polyhedral analysis



sdplr (with feasibility radius of 1.0e+3):

$$\begin{aligned} r(n,i,j) = & +7.024176e-04.n^2 +4.394909e-05.n.i \dots \\ & -2.809222e-03.n.j +1.533829e-02.n \dots \\ & +1.569773e-03.i^2 +7.077127e-05.i.j \dots \\ & +3.093629e+01.i -7.021870e-04.j^2 \dots \\ & +9.940151e-01.j +4.237694e+00 \end{aligned}$$

Successive values of  
 $r(n, i, j)$  for  $n = 10$  on  
loop entry



# Termination of a concurrent program

<pre>[  1: while [x+2 &lt; y] do   2:   [x := x + 1]     od   3:      1: while [x+2 &lt; y] do   2:   [y := y - 1]     od   3:  ]</pre>	<p>interleaving</p> <p>→</p>	<pre>while (x+2 &lt; y) do   if ?=0 then     x := x + 1   else if ?=0 then     y := y - 1   else     x := x + 1;     y := y - 1   fi fi od</pre>
---	------------------------------	--

penbmi:  $r(x,y) = 2.537395e+00.x + -2.537395e+00.y +$   
 $-2.046610e-01$





# Termination of a fair parallel program

```
[[ while [(x>0)|(y>0)] do x := x - 1] od ||  
   while [(x>0)|(y>0)] do y := y - 1] od ]]
```

interleaving  
+ scheduler  
→

$\{m \geq 1\}$  ← termination precondition determined by iterated  
forward/backward polyhedral analysis

```
t := ?;  
assume (0 <= t & t <= 1);  
s := ?;  
assume ((1 <= s) & (s <= m));  
while ((x > 0) | (y > 0)) do  
  if (t = 1) then  
    x := x - 1  
  else  
    y := y - 1  
  fi;  
  s := s - 1;
```

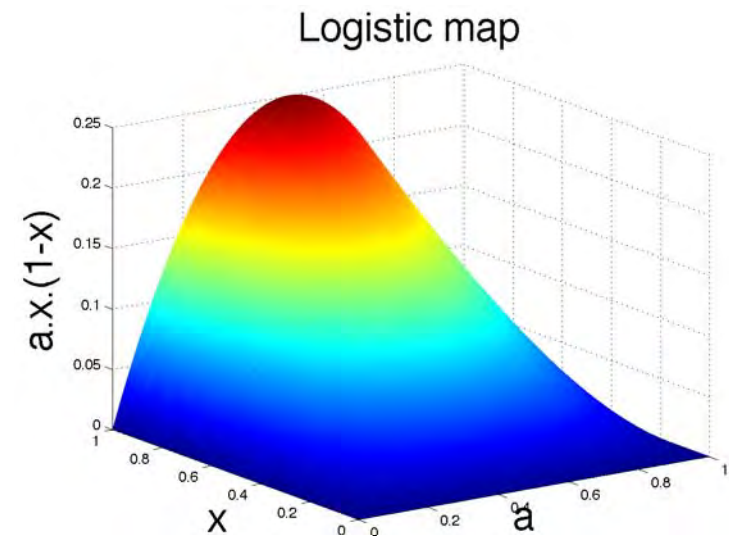
```
if (s = 0) then  
  if (t = 1) then  
    t := 0  
  else  
    t := 1  
  fi;  
  s := ?;  
  assume ((1 <= s) & (s <= m))  
else  
  skip  
fi  
od;;
```

**penbmi:**  $r(x,y,m,s,t) = +1.000468e+00.x + 1.000611e+00.y$   
 $+2.855769e-02.m - 3.929197e-07.s + 6.588027e-06.t + 9.998392e+03$



# Semidefinite programming relaxation for polynomial programs

```
eps = 1.0e-9;  
while (0 <= a) & (a <= 1 - eps)  
    & (eps <= x) & (x <= 1) do  
    x := a*x*(1-x)  
od
```



Write the verification conditions in polynomial form, use **SOSTool** to relax in semidefinite programming form.

**SOSTool+SeDuMi:**

$$r(x) = 1.222356e-13 \cdot x + 1.406392e+00$$



## When constraint resolution fails...

Infeasibility of the constraints does not mean “non termination” but simply **failure**:

- There can be a rank function of a different form (e.g. quadratic while looking for a linear one),
- The solver may have failed (e.g. add a shift).



# Coffee: Conclusion



# Numerical errors

- LMI solvers do numerical computations with **rounding errors**, shifts, etc
- rank function is subject to **numerical errors**
- the hard point is to **discover** a candidate for the rank function
- much less difficult, when it is known, to **re-check** for satisfaction (e.g. by static analysis)



# Invariance for Euclidian division

```
assume (y > 0);  
q := 0;  
r := x;  
while (y <= r) do  
    r := - y + r;  
    q := q + 1  
od
```

yalmip bmi:

$1.337645e-04*x + 2.484973e-04*q*y + 1.588933e-03*r \geq 0$

which is not false!

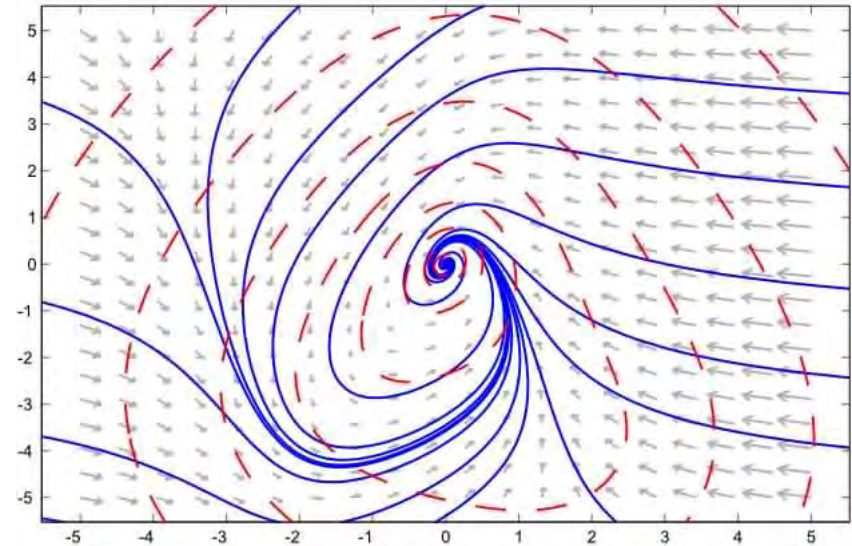


# Digestif: Questions



## Seminal work

- LMI case, Lyapunov 1890, “an invariant set of a differential equation is stable in the sense that it attracts all solutions if one can find a function that is bounded from below and decreases along all solutions outside the invariant set”.





# THE END

I hope you had a good and *relaxed*  
semantics lunch

